

DATA SHEET

Hall Effect Current Sensor

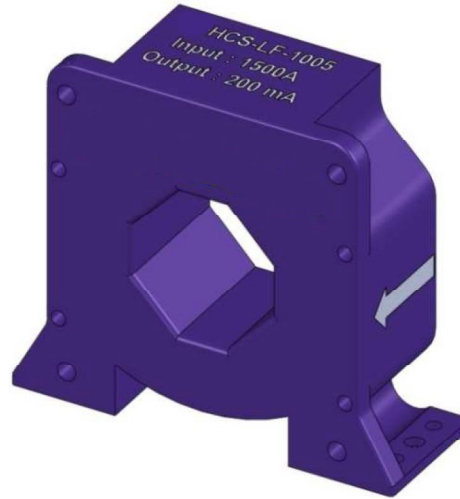
PN : HCS-LF1005

IPN = 500A - 1000A

Features

- Closed loop
- High accuracy
- Supply voltage : ± 15 to ± 24 V DC
- Current output
- Through hole primary
- Can be customized

Good linearity
Fast response time
Low temperature drift
High anti-jamming capability
Strong current overload



Applications

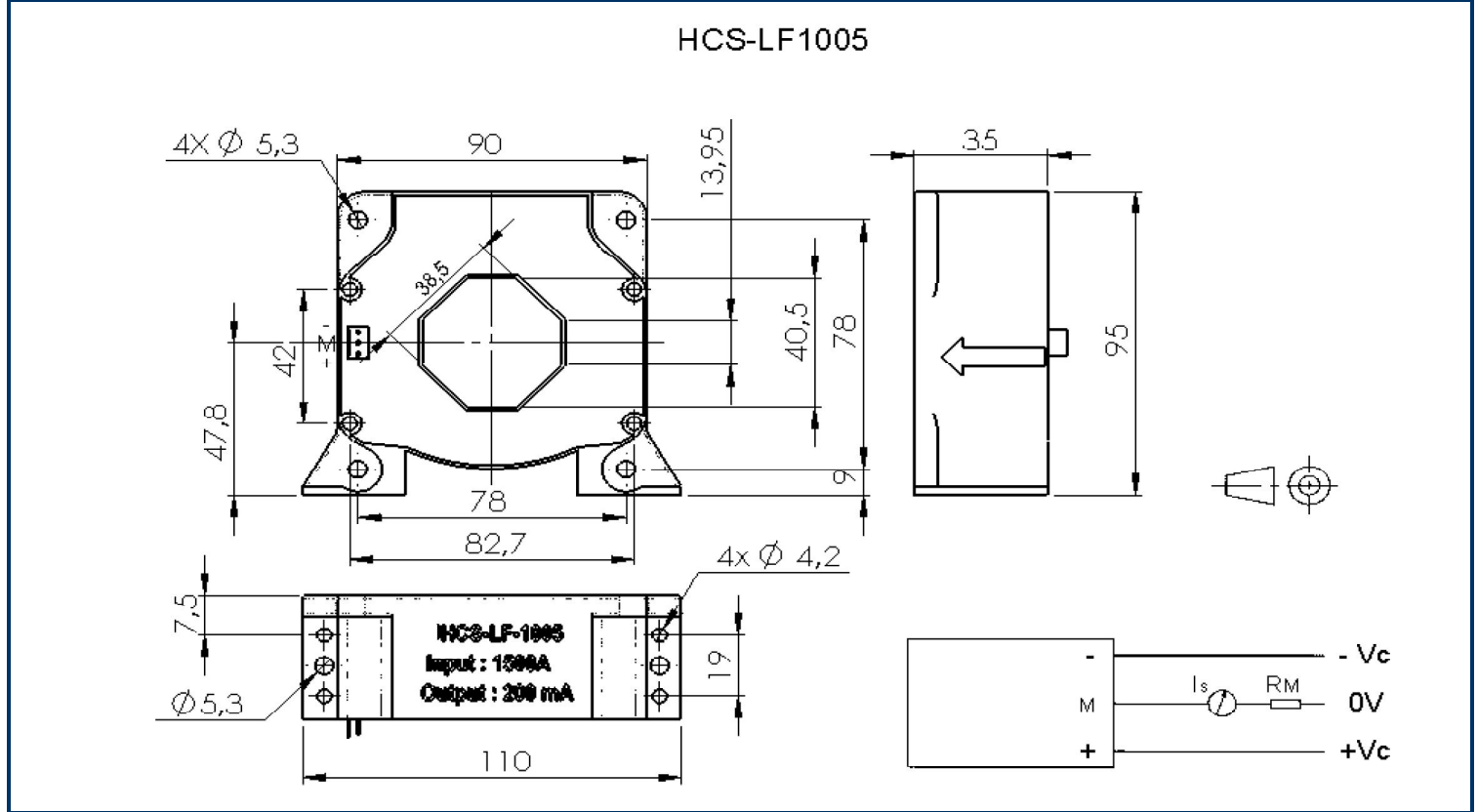
- AC/DC variable speed motor driver
- Battery applications
- Uninterruptible power supplies (UPS)
- Power supplies for welding applications

ELECTRICAL DATA

HCS-LF1005-...		500A	1000A	
Nominal rms current I_{PN} (A)		500	1000	
Sensed current range I_{PM} (A)		± 1200	± 1500	
Measuring resistance with $V_C =$	± 15 V	@ $\pm I_P$ (A)	500	1000
		$R_M \max(\Omega) =$	100	31
		@ $\pm I_P \max$ (A)	1200	1500
		$R_M \max(\Omega) =$	19	7
	± 24 V	@ $\pm I_P$ (A)	500	1000
		$R_M \max(\Omega) =$	180	71
		@ $\pm I_P \max$ (A)	1200	1500
		$R_M \max(\Omega) =$	52	34
Coil turns ratio K ($P^y:S^y$)		1:5000		
Secondary coil resistance R_S (Ω)		39		
Rated output current I_{SN} (mA)		100	200	
Supply voltage V_C (Vdc)		$\pm 12^{\pm 5\%}$ to $\pm 24^{\pm 5\%}$		
Static current consumption I_{CO} (mA)		≤ 28		
Current consumption I_C (mA)		$28 + I_S$		

ACCURACY DYNAMIC PERFORMANCE			GENERAL & ISOLATION CHARACTERISTICS		
Accuracy X_G @ I_{PN} , $T=25^\circ\text{C}$	$\pm 0,2$	%	Operating temperature	-40 to +85	$^\circ\text{C}$
Zero offset Current I_O @ $I_P=0$, $T=25^\circ\text{C}$	$\leq \pm 0,2$	mA	Storage temperature	-40 to +125	$^\circ\text{C}$
Current offset drift @ -40 $^\circ\text{C}$ to 85 $^\circ\text{C}$	$\leq \pm 0,5$	mA	Weight	510	g
Linearity error ϵ_L	$\leq 0,1$	% FS	Insulation voltage (50Hz, 1mm)	6	KV
di/dt accurately followed	> 100	A/ μs			
Response time t_r	< 1	μs			
Bandwidth (-3db)	DC to 150	kHz			

DIMENSIONS



MECHANICAL CHARACTERISTICS

General tolerance	$\pm 0,5$ mm	
Octagonal through hole size	min 38,5 mm / max 40,5 mm	
Transducer fastening	vertical installation	4 holes $\phi 4,2$ and 4 holes $\phi 5,3$ mm
	horizontal installation	4 holes $\phi 5,3$ mm
Terminal connection	Molex 6410	

Cautions :

- I_s is positive when I_p flows in accordance with the arrow direction (see the top of the sensor);
- Primary conductor temperature should not exceed 100 $^\circ\text{C}$;
- Best dynamic performances (di/dt and response time) are achieved with a single electrical conductor completely filling the through hole;
- To achieve the best magnetic coupling, the primary winding must be wound around the top edge of the sensor;
- For the required connection circuit, see the drawing above.

WARNING : Incorrect wiring may cause damage to the sensor.